

# 8xPDIF-S

8x channel differential pressure sensor with CAN bus

SN: P#####

Texense sensors are designed for data logging. Should the users want to include this sensor in a closed loop system, they must undertake total responsibility from doing so.

Measurement features			
Available ranges		±50 to ±1000	mBar
		±0.7 to ±15	PSI
Sensitive Element		Piezo resistive Cells	
Proof pressure <sup>(1)</sup>	≤ ±350mbar range	1400	mbar
	±1000mbar range	3000	
Calibrator		Mensor CPC 4000	
Accuracy		±0.5	% FS
Non linearity / Hysteresis		±0.7	% FS
Offset Drift		±0.5	% FS
Sensitivity drift		0.5	%
Sampling Frequency		200	Hz
CAN features			
CAN bus standard		2.0A or 2.0B	
Baudrate		125K to 1M	bps
Output data frequency		1Hz to 200Hz, or on trig	
Electrical features			
Supply Voltage		6 to 16	V
Supply Current		30	mA
Mechanical features			
Dimensions		See 5Mechanical drawing	
Material		Aluminum	
Weight		80	g
Internal gasket		EPDM 70sh	
Environment			
Protection		IP64	
Vibration test		20Gpp 5'	
Shock		500	G
Operating Temp		+5 to +85	°C
Storage Temp		-40 to +125	°C
Humidity		This sensor withstands high humidity. Avoid water entering in the tube as well as condensation, it may block the pressure	

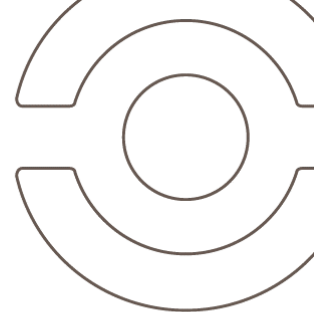
Date		Operator	
Customer			
Order			
Product Ref	8xPDIF-S-#x#-####		
SW version	V#.#		

Sensor Readings			
Channel	at mBar	at 0 mBar	at mBar
1			
2			
3			
4			
5			
6			
7			
8			

Software setup			
CAN	<input checked="" type="checkbox"/> 2.0A	<input type="checkbox"/> 2.0B	-
CAN output	<input checked="" type="checkbox"/> STD	<input type="checkbox"/> MUX	-
Baudrate	1M		bps
Frequency	10		Hz
Rx trig ID	0x7F0		-
Tx1 ID	0x3F0		-
Tx2 ID	0x3F4		-
Unit	<input checked="" type="checkbox"/> 0.1mBar/bit	<input type="checkbox"/> 1mPSI/bit	-

Factory setup			
Autozero	<input checked="" type="checkbox"/> Enable	<input type="checkbox"/> Disable	
CAN 120Ω termination resistor	<input type="checkbox"/> Connected	<input checked="" type="checkbox"/> Not connected	

(1) Do not blow into the tubes with the mouth or a compressed air line

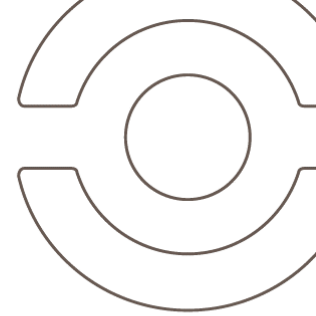


## Mechanical drawing

Manifold version	Mechanical drawing
1x common port ("S-1" ordering code)	
2x common port ("S-2" ordering code)	
8x common port ("S-8" ordering code)	

## Pinout

Cable		
5x26AWG FEP tinned copper braided cable 250V 200°C		
Length: 1000mm      Tubing: 50mm		
Connector: on request		
Color	Function	Pin
Red	Supply	-
Black	0V	-
White	CAN Low	-
Green	CAN High	-
Yellow	Do not connect and isolate	-
Braid	-	-



## Data output

The pressure values are provided in 16bit signed integer format. Resolution is 0.1mbar/bit or 1mPSI/bit, depending on configured unit.

### Standard CAN (interframe spacing 2ms)

Frame #1 (default Tx1 Frame ID: 0x03F0)

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x03F0	Channel 1 MSB	Channel 1 LSB	Channel 2 MSB	Channel 2 LSB	Channel 3 MSB	Channel 3 LSB	Channel 4 MSB	Channel 4 LSB
	Pressure 1		Pressure 2		Pressure 3		Pressure 4	

Frame #2 (default Tx2 Frame ID: 0x03F4)

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x03F4	Channel 5 MSB	Channel 5 LSB	Channel 6 MSB	Channel 6 LSB	Channel 7 MSB	Channel 7 LSB	Channel 8 MSB	Channel 8 LSB
	Pressure 5		Pressure 6		Pressure 7		Pressure 8	

### Multiplexed CAN Data output (interframe spacing 1.5ms)

Frame #1 (default Tx1 Frame ID: 0x03F0, default Sensor ID: 0xF4)

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x03F0	Sensor ID	Multiplexed Msg ID = 0	Channel1 MSB	Channel1 LSB	Channel2 MSB	Channel2 LSB	Channel3 MSB	Channel3 LSB
			Pressure 1		Pressure 2		Pressure 3	

Frame #2 (default Tx1 Frame ID: 0x03F0, default Sensor ID: 0xF4)

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x03F0	Sensor ID	Multiplexed Msg ID = 1	Channel4 MSB	Channel4 LSB	Channel5 MSB	Channel5 LSB	Channel6 MSB	Channel6 LSB
			Pressure 4		Pressure 5		Pressure 6	

Frame #3 (default Tx1 Frame ID: 0x03F0, default Sensor ID: 0xF4)

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x03F0	Sensor ID	Multiplexed Msg ID = 2	Channel7 MSB	Channel7 LSB	Channel8 MSB	Channel8 LSB	Signed char	0
			Pressure 7		Pressure 8		Internal Temp. (°C)	

## Data input

### Trig frame

Rx Frame (default Rx Frame ID: 0x07F0)

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x07F0	Sensor ID	Multiplexed Msg ID	Don't Care					
ID / 0xFF (all sensors)		0,1,2 / 0xFF(all Msg)						

### Auto-zero command (optional)

Command input frame

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x07F1	0xFF	-	-	-	-	-	-	0x01

Acknowledge output frame

ID	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x07F3	0xFF	Serial Number				0x00	0x00	0x01

This command can be used to re-zero all channels. Each time the sensor will receive the above CAN frame, the autozero function will be launched (except during first second after power-on). When autozero function is launched, a "customer offset" is set up and added for each channel on top of factory calibration. Those "Customer offsets" will be stored in volatile memory. Therefore, they will be lost when switching OFF the sensor and they will be initialized to 0 when switching ON the sensor.

## Changing parameters

Must be setup according to Texense CAN protocol, or by using the tWist® software (texense Windows software tool) with the tSIB (texense Smart Interface Box).

N°	Parameter	Raw values	Values	Comments	
0x00	Baudrate	0x00	CAN2.0A 1Mbps	Default	
		0x01	CAN2.0A 500 Kbps		
		0x02	CAN2.0A 250 Kbps		
		0x03	CAN2.0A 125 Kbps		
		0x10	CAN2.0B 1Mbps		
		0x11	CAN2.0B 500 Kbps		
		0x12	CAN2.0B 250 Kbps		
		0x13	CAN2.0B 125 Kbps		
0x01	Emission frequency AND Standard CAN	0x00	Rx frame trigger mode		
		0x01	1 Hz		
		0x02	5		
		0x03	10	Default	
		0x04	50		
		0x05	100		
		0x06	200		
	Emission frequency AND Multiplexed CAN	0x10	Rx frame trigger mode		
		0x11	1 Hz		
		0x12	5		
		0x13	10		
		0x14	50		
		0x15	100		
		0x16	200		
0x02	Rx frame ID	if CAN2.0A: 0x1 to 0x7F0		MSB of triggering frame ID	Default 0x07F0
0x03		if CAN2.0B: 0x1 to 0xFFFF (except 0x7F1 to 0x7F3)		LSB of triggering frame ID	
0x04	Tx1 frame ID	if CAN2.0A: 0x1 to 0x7F0		MSB of data frame 1 ID	Default 0x03F0
0x05		if CAN2.0B: 0x1 to 0xFFFF (except 0x7F1 to 0x7F3)		LSB of data frame 1 ID	
0x06	Tx2 frame ID	if CAN2.0A: 0x1 to 0x7F0		MSB of data frame 2 ID	Default 0x03F4
0x07		if CAN2.0B: 0x1 to 0xFFFF (except 0x7F1 to 0x7F3)		LSB of data frame 2 ID	
0x06	if Multiplexed CAN: Sensor ID	Don't care		Not used	Default 0xF4
0x07		0 to 0xFE		Sensor ID	
0x08	Unit	0x00	PSI	0.001 PSI / bit	Default
		0x01	Bars	0.1 mBar / bit	

For complete information, contact us at [info@texense.com](mailto:info@texense.com)

## Ordering information

### Ordering ref:

#### 8xPDIF-S – Common ports – Range – Autozero

**1x1:** 1x 1mm common port (1x ref for channels 1 to 8)  
**1x1.6:** 1x 1.6mm common port (1x ref for channels 1 to 8)  
**2x1:** 2x 1mm common port (1x ref for channels 1 to 4)  
 and 1x ref for channels 5 to 8)  
**2x1.6:** 2x 1.6mm common ports (1x ref for channels 1 to 4  
 and 1x ref for channels 5 to 8)  
**8x1.6:** 8x 1.6mm common ports (1x ref per channel)

**N:** None  
**Z:** Auto-zero

**50:** ±50mbar range  
**70:** ±70mbar range  
**150:** ±150mbar range  
**200:** ±200mbar range  
**250:** ±250mbar range  
**350:** ±350mbar range  
**1000:** ±1000mbar range

ex: 8xPDIF-S-2x1-350-Z